

Appendix A: Equation of Motion

$$Power = Velocity * [Drag + Inertial + Rolling]_{Force} + \frac{(Gravity)_{work} + (Misc)_{work}}{\Delta time}$$

Aerodynamic term:

$$V \left\{ \left[\frac{1}{2} \mathbf{r} V^2 C_d A_w \right]_{FrontWheel} + (1 - protection) \left[\frac{1}{2} \mathbf{r} V^2 C_d A_w \right]_{RearWheel} + \left[\frac{1}{2} \mathbf{r} V^2 C_d A_w \right]_{Frame} + \left[\frac{1}{2} \mathbf{r} V^2 C_d A_w \right]_{rider} \right\}$$

Where:

\mathbf{r} = air density

V = velocity

C_d = drag coefficient

A = reference area (side area for wheels, frontal area for rider and frame)

Protection = reduction in C_d of rear wheel due to its proximity to frame = .25

Inertial term:

$$\mathbf{w} [I\mathbf{a}]_{Frontwheel} + \mathbf{w} [I\mathbf{a}]_{Rearwheel} + V \cdot M_{Tot} \mathbf{a}$$

Converting to linear acceleration terms and discretizing we have:

$$\mathbf{w} = \frac{V}{R}$$

$$\mathbf{a} = \frac{d\mathbf{w}}{dt} = \frac{d}{dt} \left(\frac{V}{R} \right) = \frac{1}{R} \frac{\Delta V}{\Delta t}$$

$$a = \frac{\Delta V}{\Delta t}$$

∴

$$V \left\{ \left[I \frac{1}{R^2} \frac{\Delta V}{\Delta t} \right]_{Frontwheel} + \left[I \frac{1}{R^2} \frac{\Delta V}{\Delta t} \right]_{Rearwheel} + M_{Tot} \frac{\Delta V}{\Delta t} \right\}$$

Where:

\mathbf{w} = rotational velocity (rad/s)

\mathbf{a} = angular acceleration

R = wheel radius

Dt = change in time

DV = change in velocity

M_{Tot} = total mass including bike, rider, wheels, tires

I = moment of inertia

Rolling resistance term:

$$V[C_{rr}M_{Tot}g]$$

Where:

C_{rr} = coefficient of rolling resistance

g = gravitational acceleration (9.81 m/s²)

Gravitational term:

$$M_{Tot}g \frac{\Delta h}{\Delta t}$$

Where:

Dh = change in elevation

Final equation of motion:

$$V \left\{ \left[\frac{1}{2} rV^2 C_d A_w \right]_{FrontWheel} + (1 - protection) \left[\frac{1}{2} rV^2 C_d A_w \right]_{Re arWheel} + \left[\frac{1}{2} rV^2 C_d A_w \right]_{Frame} + \left[\frac{1}{2} rV^2 C_d A_w \right]_{rider} \right. \\ \left. + \left[I \frac{1}{R^2} \frac{\Delta V}{\Delta t} \right]_{Frontwheel} + \left[I \frac{1}{R^2} \frac{\Delta V}{\Delta t} \right]_{Re arwheel} + M_{Tot} \frac{\Delta V}{\Delta t} \right. \\ \left. + C_{rr} M_{Tot} g \right.$$

$$+ M_{Tot} g \frac{\Delta h}{\Delta t} = Power_{rider}$$